

## JACOBSON HOLMAN PLLC

400 SEVENTH STREET, N.W. WASHINGTON, D.C. 20004-2201

LIST OF PATENTS AND PUBLICATIONS FOR APPLICANT'S INFORMATION DISCLOSURE STATEMENT

ATTY. DOCKET NO.: P71359US0 SERIAL NO.: 10/585,412 APPLICANT(S): MOREL et al			GROUP ART UNIT:  FILING DATE: July 7, 2006  Date: March 2, 2007				
*****	*****		******	*****	*****	****	****
	DOCIMENT	U.S. PA	TENT DOCUMENTS		SUB-	DII TWO	
*EXAMINER	DOCUMENT NUMBER	DATE	NAME	CLASS	CLASS	FILING	
INITIAL	NOMBER	DATE		CDADD	CHADD	(II Appro	JDI Tace/
AA							
AB	<del></del>						
AC							
AD	<del> </del>						
AE							
AF							
AG							
AH							
AI							
<del></del>		-					
	DOCUMENT NUMBER	FOREIGN P	ATENT DOCUMENTS  COUNTRY	<u>CLASS</u>	SUB- CLASS	TRANSLA	ATION (NO)
7. T	0624246	11/17/04	EDO			х	•
AL	0624346 W001 (70117	<u>11/17/94</u>	EPO	<del></del>		X	<del></del>
AM	<u>WO01/70117</u> 0548872	<u>09/27/01</u> 06/30/93	WIPO EPO			X	
AN	1285634	08/30/93	EPO			X	
AO	1203034	02/20/03	<u> </u>				
AP							
*****	*****	*****	******	*****	*****	****	****
OTHER	ART (Includ	ing Author,	Title, Date, Per	tinent Pa	ages, E	tc.)	
AR	WAGNER C R	ET AL: "The	role of force for	eedback i	n sura	erv:	
	WAGNER C R ET AL: "The role of force feedback in surgery: analysis of blunt dissection", HAPTIC INTERFACES FOR VIRTUAL						
			ERATOR SYSTEMS,				
			OSIUM ON ORLANDO				_ I
	2002, LOS ALAMITOS, CA, USA, IEEE COMPUT. SOC, US, PAGE(S) 68-74						
	XP010590539 ISBN: 0-7695-1489-8						
AS	ATI INDUSTRIAL AUTOMATION: "Multi-Axis Force/Torque Sensor F/T",						
	11 avril 2003 (2003-04-11), ATI INDUSTRIAL AUTOMATION 2003						
			USA XP00228063				=
EXAMINER			DATE CONSIDERED		· · ·		<del></del>

<sup>\*</sup> EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant(s).